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Using Frequency-Offset Estimation Schemes for Acquisition

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- Outline:**
- ⇒ Acquisition in Systems with Large Frequency Offsets
 - ⇒ Comparison of Acquisition and Frequency Estimation Schemes
 - ⇒ Advanced Frequency Offset Estimators (Time Domain)
 - ⇒ Simulation Results
 - ⇒ Conclusions and Outlook



System Model

- ⇒ No data modulation considered
- ⇒ Received samples $r(k)$ given by:

$$r(k) = \sqrt{E_s} e^{j(2\pi\Delta f k T + \Phi)} + n(k), \quad 0 \leq k \leq L - 1$$

- × k : time index
- × L : length of observed sequence
- × E_s : symbol energy
- × T : symbol interval
- × f, ϕ : deterministic, unknown, frequency- and phase-offset
- × $n(k)$: additive white Gaussian noise



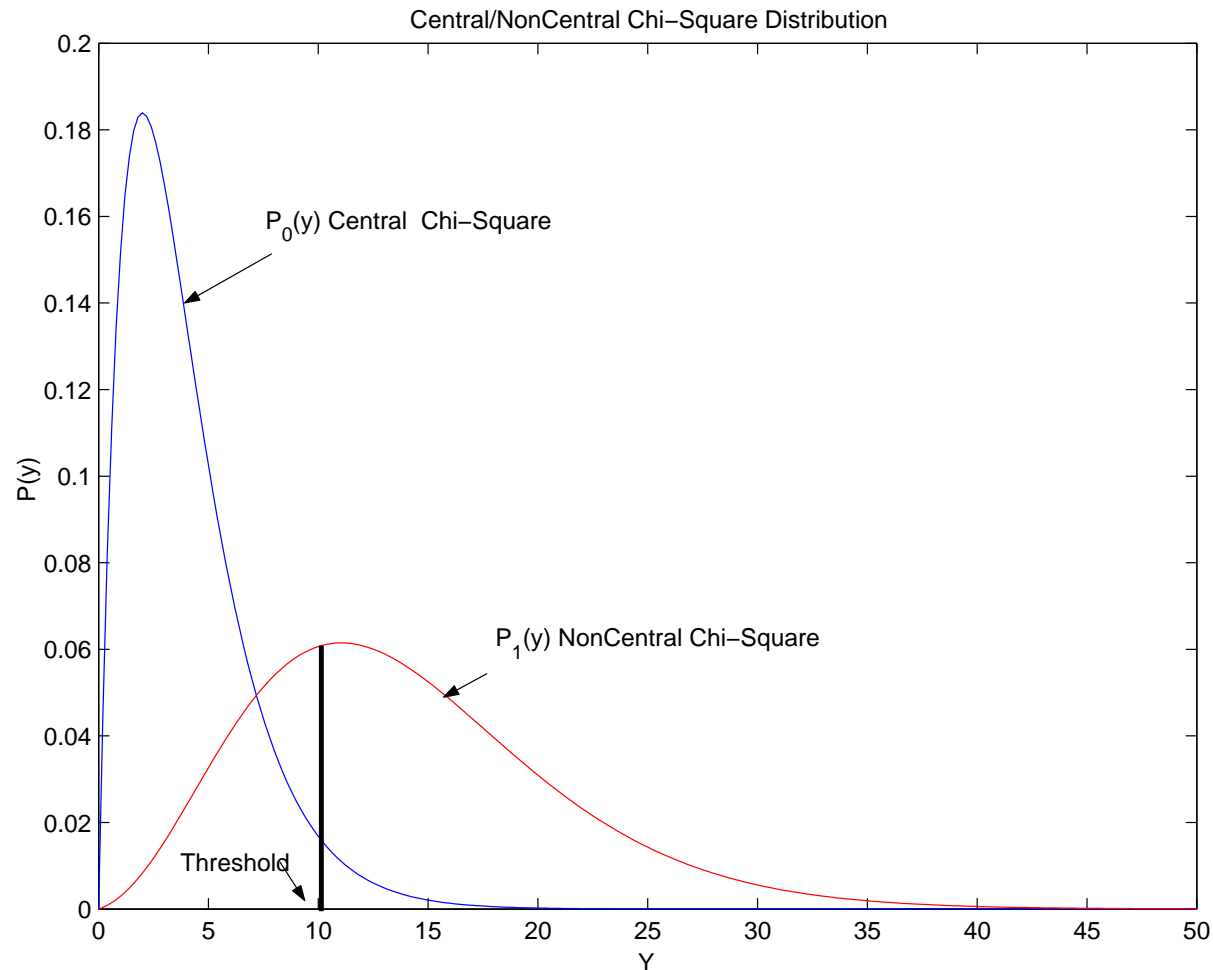
Acquisition - No Frequency Offsets

- ⇒ Form Decision variable as: $Z_C = \left| \sum_{k=0}^{L-1} r(k) \right|^2$
- ⇒ Compare Z to threshold θ :
 - ✗ If $Z < \theta$ declare preamble not present
 - ✗ If $Z > \theta$ declare preamble present
 - * If preamble present, successful detection ($\rightarrow P_D$)
 - * If preamble not present, false alarm ($\rightarrow P_{FA}$)
- ⇒ Employ power-scaled threshold, which yields a constant false alarm rate P_{FA} :

$$\theta = - \left(\sum_{k=0}^{L-1} |r(k)|^2 \right) \ln(P_{FA})$$



Acquisition - Probability Density Functions



⇒ Example for resulting probability density functions



Acquisition - Effect of Frequency Offsets

- Frequency Offset Δf causes degradation $D(\Delta f)$ for sequence of length L :

$$D(\Delta f) = \left(\frac{\sin(\pi L \Delta f T)}{\pi L \Delta f T} \right)^2$$

- Use frequency dependant decision variable:

$$Z(f) = \left| \sum_{k=0}^{L-1} r(k) \exp(-j2\pi k f T) \right|^2$$

- Possible implementation via FFT, which evaluates $Z\left(\frac{m}{LT}\right)$, $0 \leq m < L$



Acquisition - Coherent Sample Combining

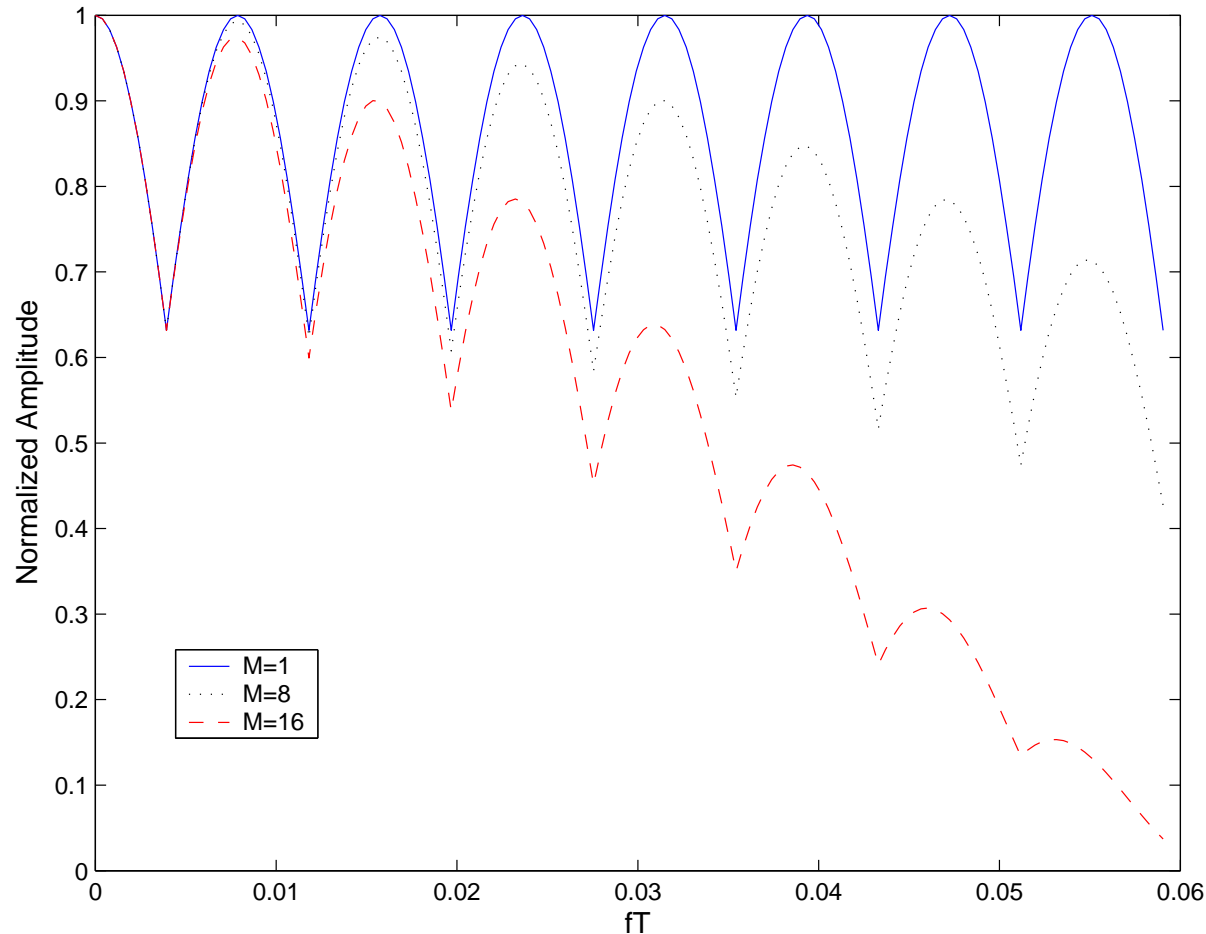
- ⇒ In most applications frequency offset small compared to the signal bandwidth \Rightarrow phase rotation between succeeding samples is small
- ⇒ Small frequency offsets allow to perform sample combining in original sequence, to obtain a new reduced length sequence $r_c(l)$:

$$r_c(l) = \sum_{k=0}^{M-1} r(k + lM)$$

- ⇒ Reduced sequence length means that a reduced length FFT is evaluated



Acquisition - Effect of Coherent Sample Combining



- ➔ Signal degradation due to offset relative to bins and increasing combining rate M .



Acquisition - Post Detection Integration (PDI)

- ⇒ Non-coherent Post Detection Integration

$$Z_{NC} = \sum_{k=0}^{\frac{L}{M}-1} |r_c(k)|^2$$

- ⇒ Differential Post Detection Integration - Absolute

$$Z_{DA} = \left| \sum_{k=1}^{\frac{L}{M}-1} r_c(k) r_c^*(k-1) \right|^2$$

- ⇒ Differential Post Detection Integration - Real

$$Z_{DR} = \text{Re} \left\{ \sum_{k=1}^{\frac{L}{M}-1} r_c(k) r_c^*(k-1) \right\}$$



Frequency Offset Estimation in Time Domain(1)

⇒ The Kay-Estimator:

Idea is to evaluate phase rotation between succeeding samples:

$$\Delta \hat{f} = \arg \left\{ \sum_{k=1}^{L-1} w(k) r(k) r^*(k-1) \right\}$$

- ⇒ Alternatively, could evaluate the sum over the phase values
- ⇒ Many advanced estimators exist that are based on the same principle
- ⇒ Many different FFT-based estimators exist



Frequency Offset Estimation in Time Domain (2)

- ⇒ Idea of advanced schemes is to evaluate phase rotation between samples of several delays:

$$R(l) = \frac{1}{L-l} \sum_{k=l}^{L-1} r(k)r^*(k-l)$$

- ⇒ Combine several $R(l)$ to generate estimate
- ⇒ Alternatively, the difference between phase angles could be evaluated



Frequency Offset Estimation in Time Domain (3)

⇒ M&M-Estimator:

Exploits several sample correlation values, but maintains estimation range by evaluating phase-differences between sample correlations:

$$R_1(l) = R(l)R^*(l - 1)$$

The decision variable is then obtained by:

$$Z_{MM} = \left| \sum_{l=1}^N \beta(l) R_1(l) \right|^2$$

where $\beta(l)$ are real coefficients that sum to unity



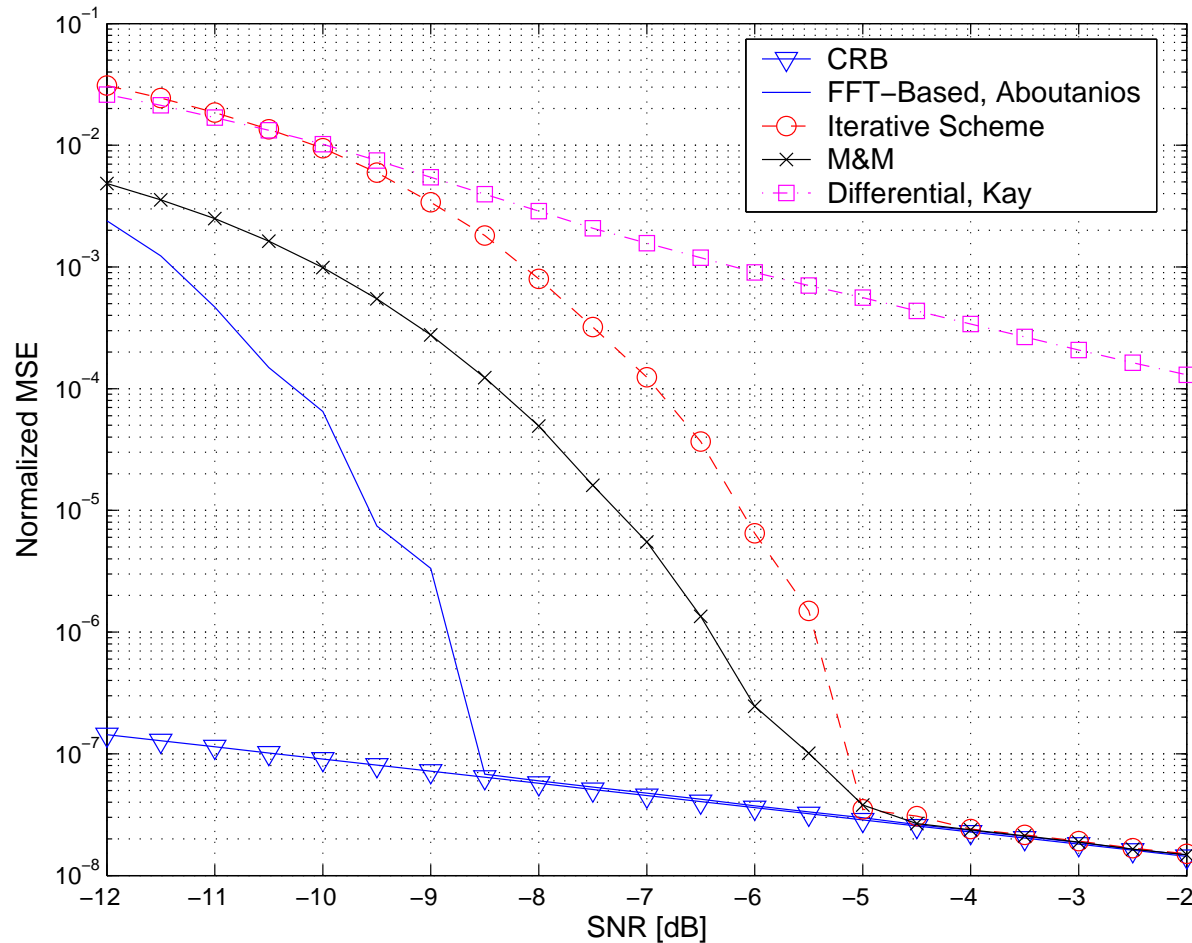
Iterative Frequency Offset Estimation

⇒ Iterative Estimation:

1. Estimate the frequency offset without (or with little) combining.
 2. Correct the frequency offset in the sequence using the current estimate from step 1).
 3. Combine a number of samples to obtain a new sequence.
 4. Continue with 1).
- ⇒ To use the scheme for acquisition, just combine all remaining elements in the last iteration ⇒ Same decision variable as in classical acquisition theory



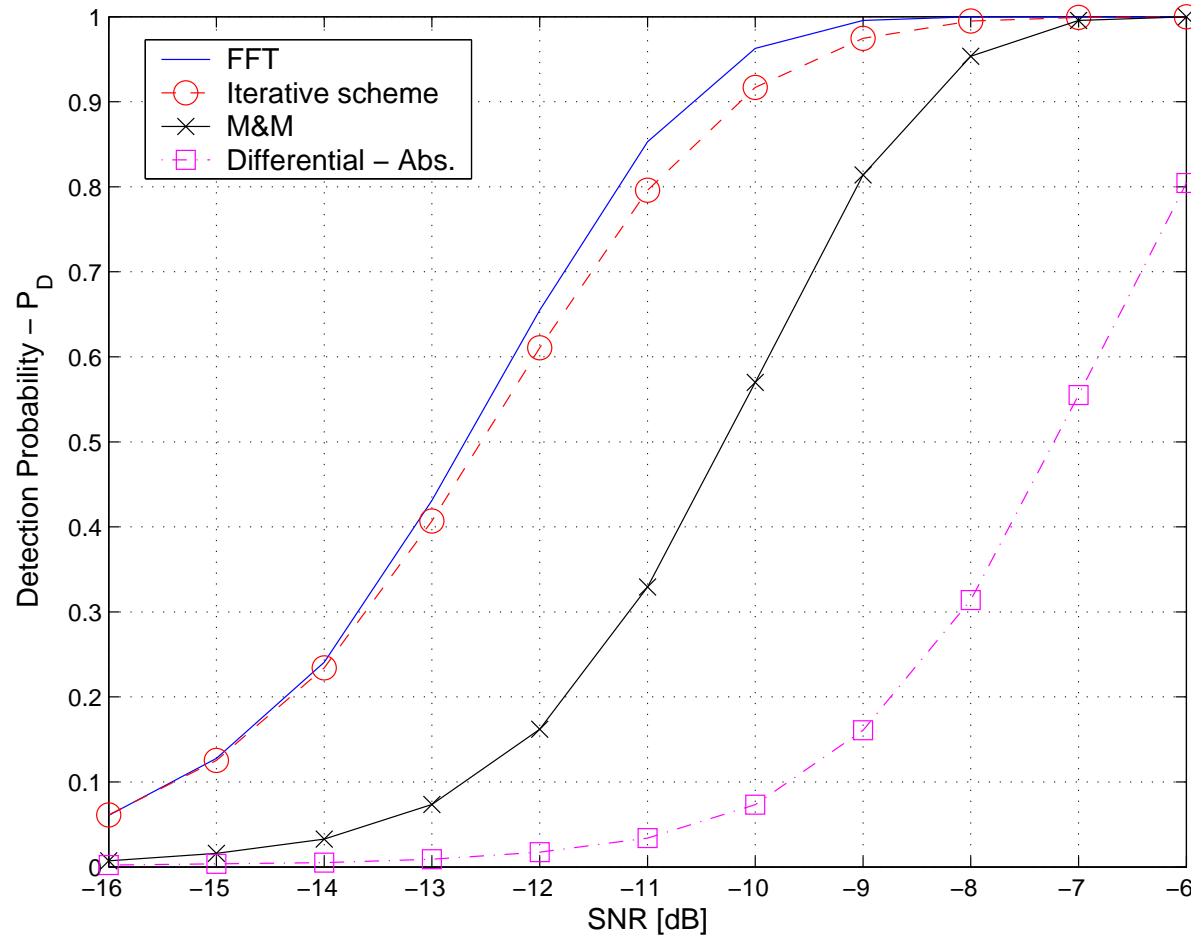
MSE of Different Frequency Offset Estimators



- ⇒ Sequence length $L = 256$, $N = 128$ for the M&M-estimator
- ⇒ Estimators have very different SNR-thresholds



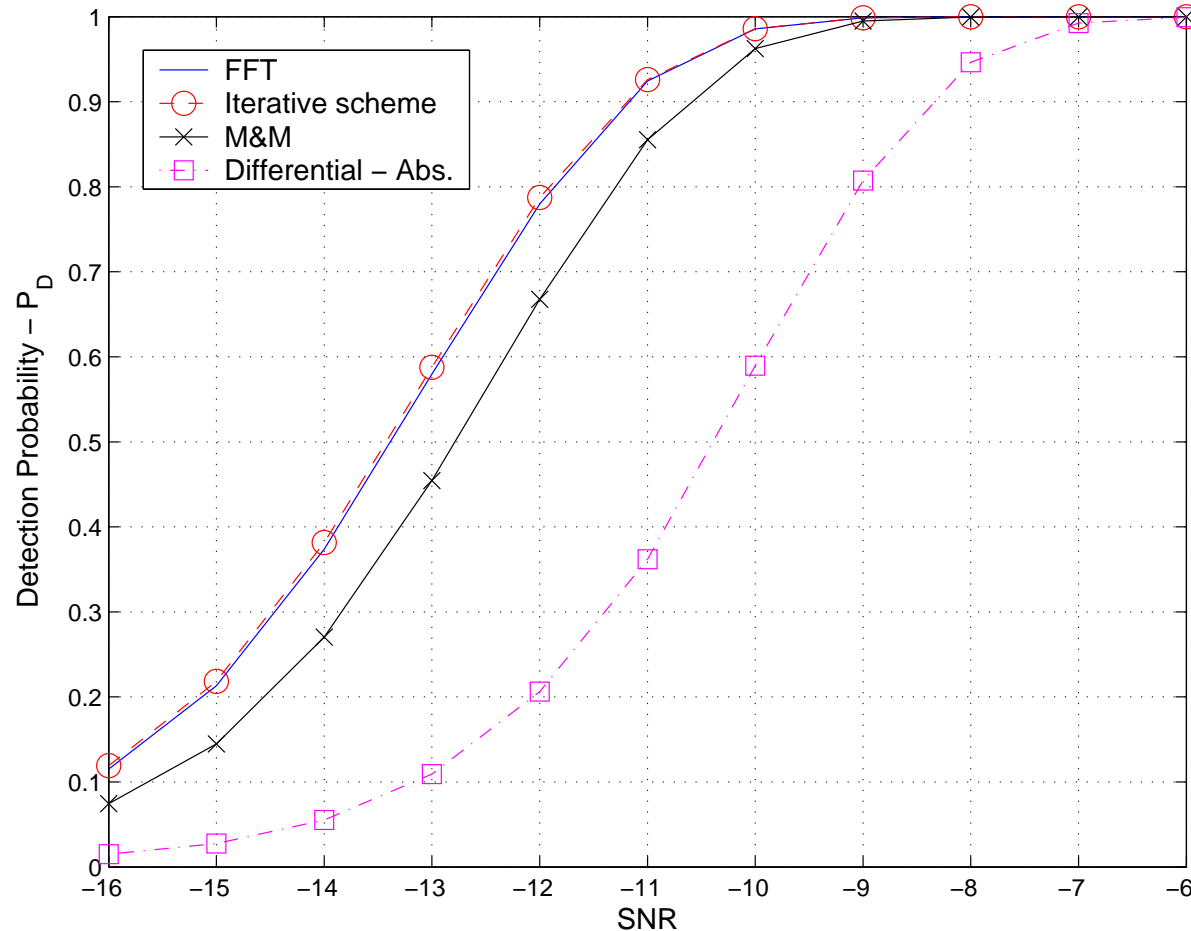
Detection Probabilities without Combining



⇒ Sequence length $L = 256$, False alarm probability $P_{FA} = 10^{-3}$, $N = 10$ for the M&M-estimator



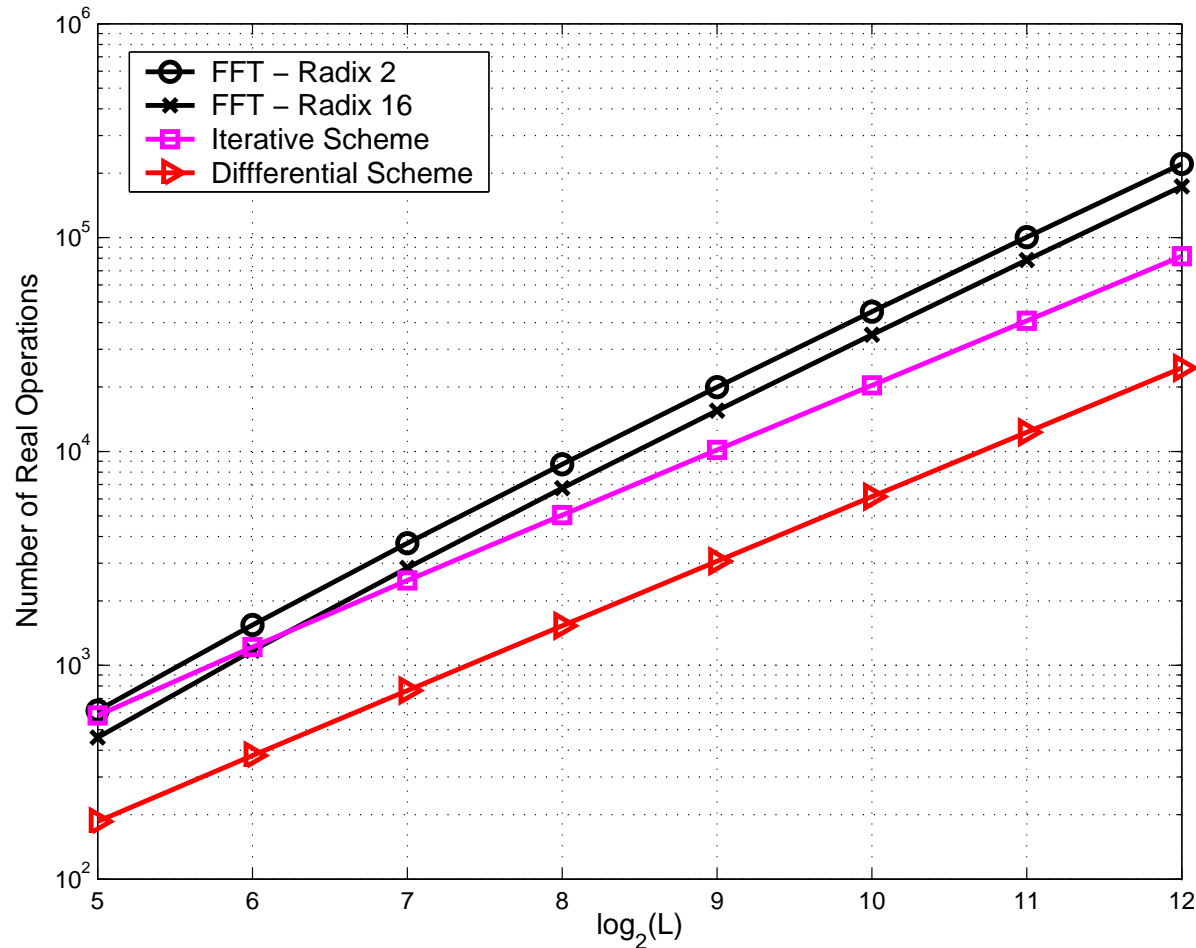
Detection Probabilities with Combining



⇒ Sequence length $L = 256$, False alarm probability $P_{FA} = 10^{-3}$, Combining factor $M = 4$, $N = 10$ for the M&M-estimator



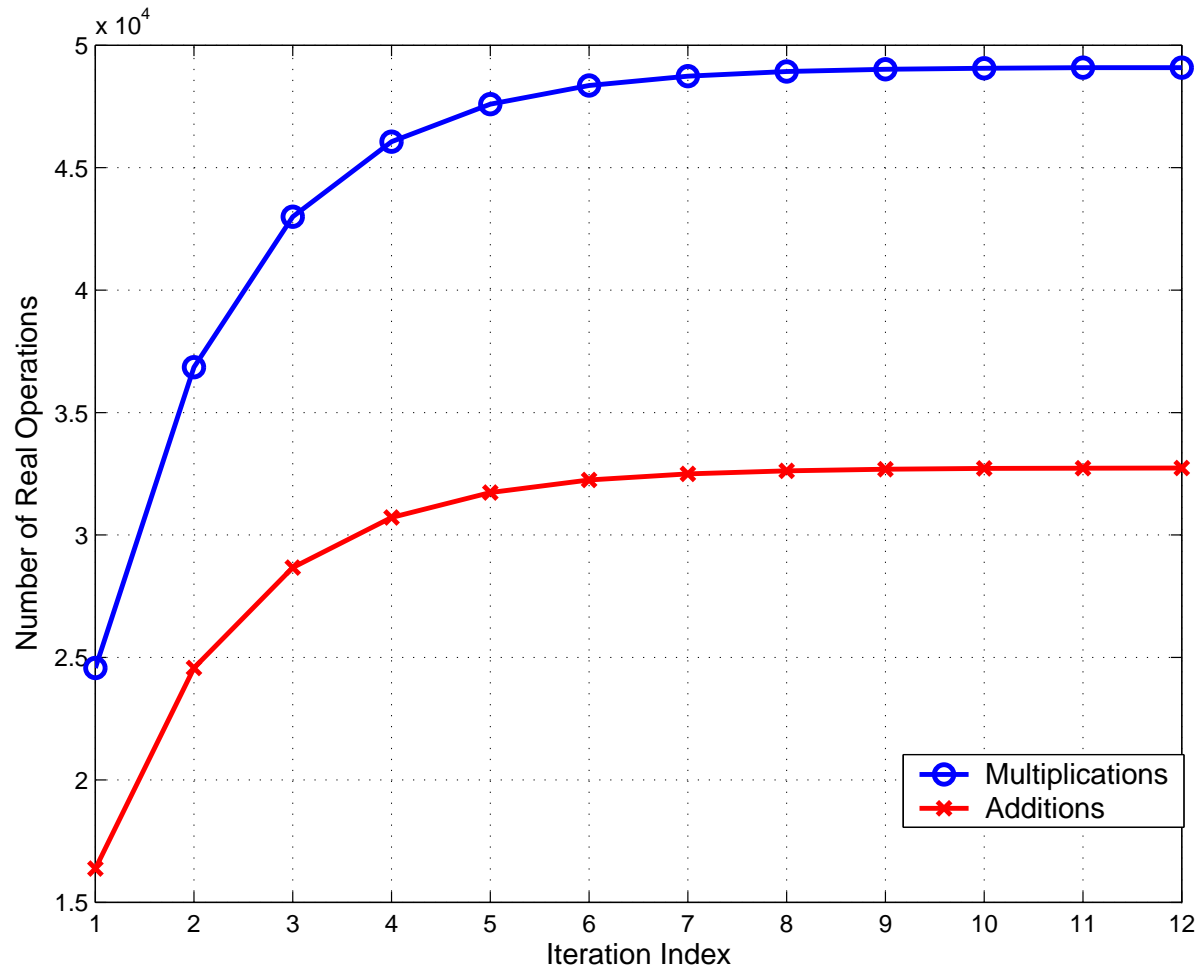
Computational Complexity of Different Schemes



- ⇒ Computational complexity for different sequence lengths L
- ⇒ Non-Padded FFT without max-search



Computational Complexity of Iterative Scheme by Iteration



⇒ Computational complexity for sequence length $L = 4096$

⇒ Initial iterations account for most of the complexity



Summary and Conclusions

- ⇒ Frequency estimation schemes can be applied to acquisition problems with small modifications
- ⇒ Several schemes can close the huge performance gap between FFT-based acquisition and simple differential schemes
- ⇒ Schemes that operate in time-domain have an inherent flexibility to trade off complexity for performance
- ⇒ Time-domain schemes do not have a frequency-dependant performance
- ⇒ Further optimization of iterative scheme possible
- ⇒ Exact derivation of the detection thresholds still an open problem